# Petri-net Based Animation with CPN Tools and BRITNeY animation

Michael Westergaard

mw@daimi.au.dk

Department of Computer Science University of Aarhus

#### **Motivation**

 High-level graphics makes it easier to demonstrate and communicate models

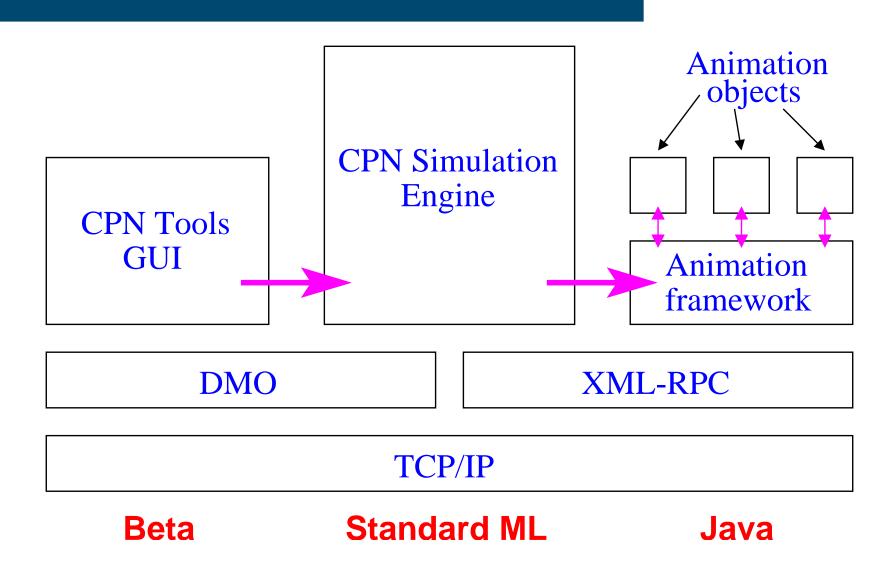
#### **Overview**

- Architecture
- Hello World
- Dining Philosophers
- Stop Signal
- A closer look at ShowModal
- Future work & conclusion

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#### **Overall Architecture**



#### Why Java?

- Well-known by many computer scientists
- Well-suited for creating graphics
- A huge number of libraries already exist ⇒ it is easy to create even very complex animation objects

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# Hello World (1/3)

The purpose of this example is

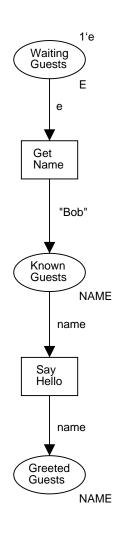
- to introduce connections
- to see the ShowModal and GetString animation objects
- to see how the animation functions can be used

## Hello World (2/3)

- We want to model part of a hotel
- We focus on the clerk at the counter
- When a guest enters the clerk asks for his name
- The clerk then greets the guest

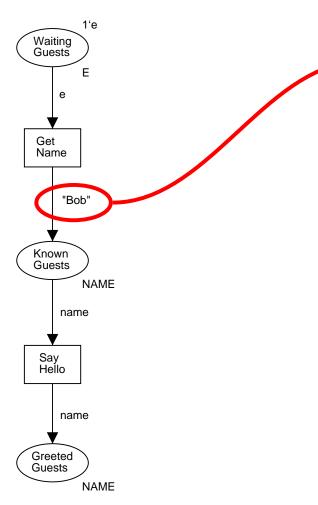


# Hello World (3/3)



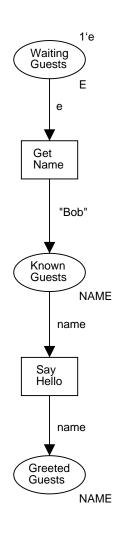
- We notice that we have hard-coded the name of the guest
- We would rather allow the user to act as the guest
- ...for this we will use some simple standard functions

## Hello World (3/3)



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# Hello World (3/3)



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# Setting up a Connection (1/2)

- In order to use the animation package, we must first set up a connection to an animation object
- In this example, we will add the declaration

```
structure msg =
   ShowModalInstance(
     val name = "Message");
```

■ This can be thought of as creating a proxy object, msg, with an interface, ShowModal, in e.g. Java

# Setting up a Connection (2/2)

■ The interface of ShowModal is:

```
sig
  val displayMessage: string -> int
end
```

That is, we can call msg.displayMessage("Hello World") to show the message "Hello World" to the user

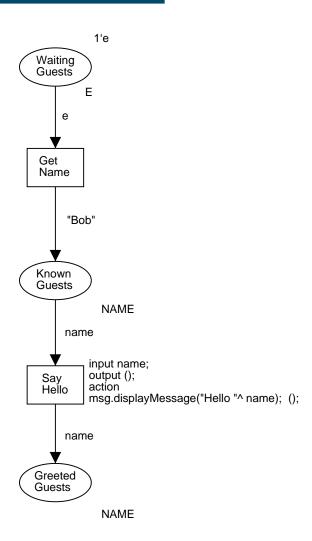
# **Using Animation Functions (1/2)**

- CPN Tools allows code-fragments to be executed whenever a transition occurs
- Code-fragments have the syntax:

```
input (...)
output (...)
action
...
```

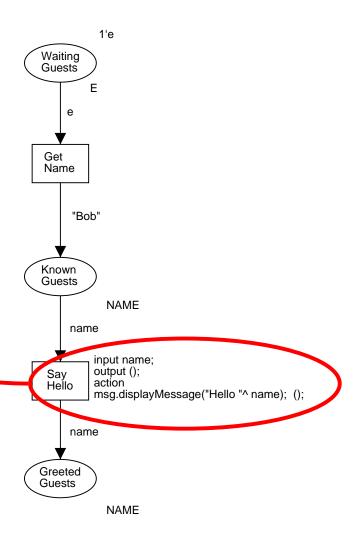
# **Using Animation Functions (2/2)**

We can use codefragments to tie the animation to our model:



# **Using Animation Functions (2/2)**

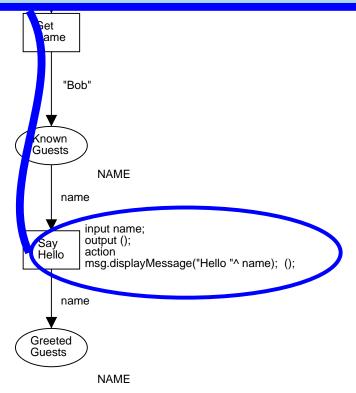
We can use codefragments to tie the animation to our model:



# **Using Animation Functions (2/2)**

```
input name;
output ();
action
msg.displayMessage("Hello " ^ name); ();
```

• We can use codefragments to tie the animation to our model:



## Asking for a Guest's Name (1/2)

■ We create a connection

```
structure input =
   GetStringInstance(
        val name = "Question");
with the interface:
sig
   val getString:
        string * string -> string
end
```

# Asking for a Guest's Name (2/2)

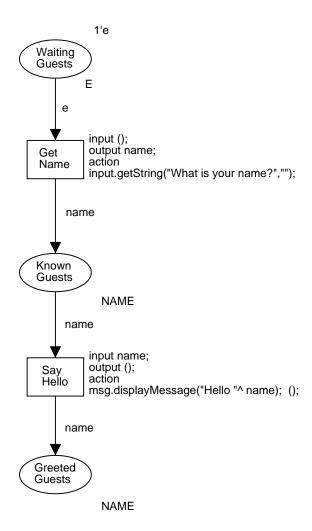
1'e

Waiting

Guests input (); output name; Get Name input.getString("What is your name?",""); name ...and use it in our-Known model Guests NAME name input name: output (); Sav msg.displayMessage("Hello "^ name); (); name Greeted Guests NAME

# Asking for a Guest's Name (2/2)

...and use it in our model



## So Far, We Have Seen...(1/3)

...how to create connections to an animation
object:
structure msg =
 ShowModalInstance(
 val name = "Message");

## So Far, We Have Seen...(2/3)

- ...2 animation object interfaces:
  - ShowModal:

```
sig
  val displayMessage: string -> int
end
```

■ GetString:

```
sig
  val getString:
    string * string -> string
end
```

## So Far, We Have Seen...(3/3)

```
...how to use connections in our nets using
code-fragments:
input name;
output ();
action
msg.displayMessage("Hello " ^ name); ();
```

#### **Overview**

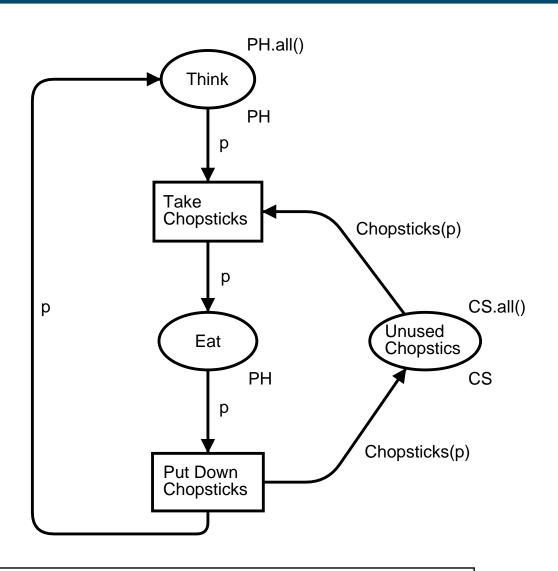
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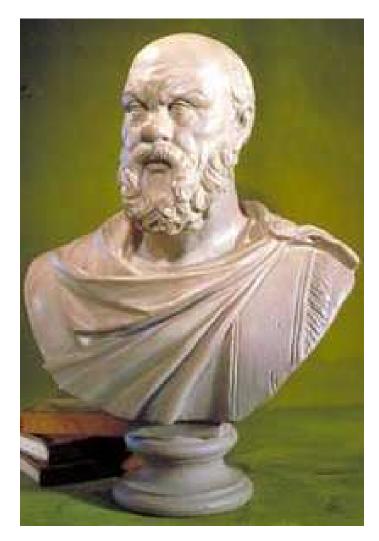
# Dining Philosophers (1/2)

#### The purpose of this example is

- to see the GraphSheet animation object
- to see how we can write small libraries using the animation functions

# Dining Philosophers (2/2)





#### **GraphSheet**

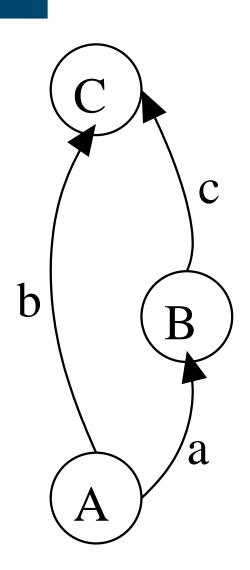
- We want to generate and draw the state-space
- For this, we will use GraphSheet:

# State-space Functions (1/2)

■ The CPN Tools state-space tool provides a number of functions:

## State-space Functions (2/2)

- SourceNode(a) = A
- DestNode(a) = B
- $\blacksquare$  st\_Node(A) = "A"
- EvalAllArcs(fn x => x)
  = [a, b, c]



## **Drawing all Nodes**

We assume a connection to a GraphSheet animation object named graph

Draw one node, A:
 graph.createVertex(st\_Node(A))

## **Drawing all Nodes**

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- Draw one node, A:
   graph.createVertex(st\_Node(A))
- Draw an arbitrary node:
   fun drawNode n =
   graph.createVertex(st\_Node(n))

## **Drawing all Nodes**

We assume a connection to a GraphSheet animation object named graph

- Draw one node, A:
   graph.createVertex(st\_Node(A))
- Draw an arbitrary node:
   fun drawNode n =
   graph.createVertex(st\_Node(n))
- Draw all nodes: EvalAllNodes(drawNode)

## **Drawing all Arcs**

Draw one arc, a, from A to B: graph.createEdge( st\_Node(A), st\_Node(B), "")

## **Drawing all Arcs**

Draw one arc, a, from A to B: graph.createEdge( st\_Node(A), st\_Node(B), "")

Draw one arc, a:
 graph.createEdge(
 st\_Node(SourceNode(a)),
 st Node(DestNode(a)), "")

## **Drawing all Arcs**

Draw one arc, a:
 graph.createEdge(
 st\_Node(SourceNode(a)),
 st Node(DestNode(a)), "")

Draw an arbitrary arc:

```
fun drawArc a =
  graph.createEdge(
    st_Node(SourceNode(a)),
    st_Node(DestNode(a)), "")
```

### **Drawing all Arcs**

Draw one arc, a:
 graph.createEdge(
 st\_Node(SourceNode(a)),
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Draw an arbitrary arc:

```
fun drawArc a =
  graph.createEdge(
    st_Node(SourceNode(a)),
    st_Node(DestNode(a)), "")
```

Draw all arcs: EvalAllArcs(drawArc)

### All Drawing-code (1/3)

```
fun drawNode n =
  graph.createVertex(st_Node(n))
EvalAllNodes(drawNode)
fun drawArc a =
  graph.createEdge(
      st Node(SourceNode(a)),
      st Node(DestNode(a)), "")
EvalAllArcs(drawArc)
```

## All Drawing-code (2/3)

- The code does not depend on the net at all
- We may want to draw state-spaces for other nets as well
- creating a small library seems like a good idea
- We will then be able to draw a state-space by issuing:

```
use("visualise.sml")
```

### All Drawing-code (3/3)

- A slightly more elaborate library has been implemented
  - Support for drawing only parts of a state-space
  - Support for better names of nodes and arcs
- Using this library, drawing a state-space is as simple as:

```
use("visualise.sml");
NiceLabels();
DrawEntireGraph();
```

### So Far, We Have Seen...(1/2)

```
... the GraphSheet animation object interface:
sig
  val createVertex: string -> int
  val createEdge:
         string * string * string
           -> int
  val doLayout: unit -> int
  val export: unit -> int
end
```

### So Far, We Have Seen...(2/2)

#### ...how to

- use GraphSheet with the state-space functions
- create a small library for drawing state-spaces, which can be used as:

```
use("visualise.sml");
NiceLabels();
DrawEntireGraph();
```

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# Stop Signal (1/3)

#### The purpose of this example is

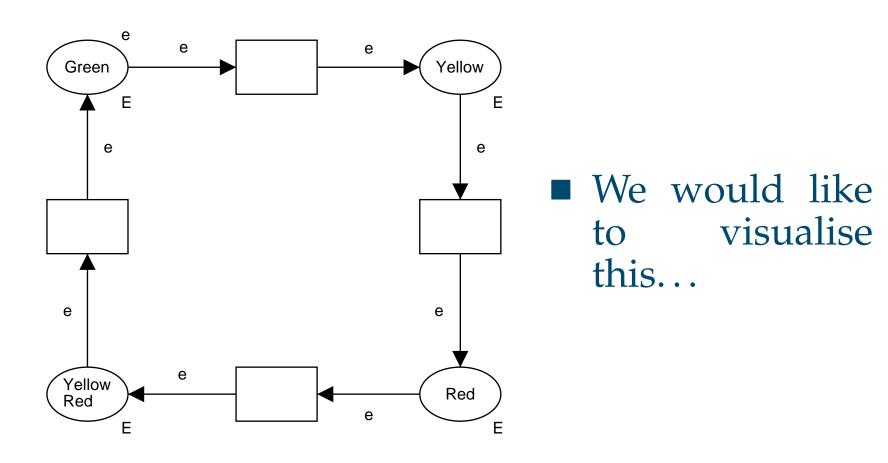
- to introduce the SceneBeans animation object
  - ♦ Creating animation-description files
  - ♦ Loading animation-description files
  - ♦ Invoking commands in the animation
  - ♦ Setting parameters in the animation
  - ♦ Listening for events from the animation

## Stop Signal (2/3)

- A danish stop signal cycles between the colours:
  - ♦ green
  - ♦ yellow
  - ♦ red
  - ♦ yellow + red
- We want to model this



# Stop Signal (3/3)



### SceneBeans (1/3)

- From the SceneBeans homepage<sup>a</sup>: "SceneBeans is a Java framework for building and controlling animated graphics... It is used in the LTSA tool to animate formal models of concurrent systems"
- SceneBeans was designed and implemented by Nat Pryce of Imperial College, London

ahttp://www-dse.doc.ic.ac.uk/Software/SceneBeans/

### SceneBeans (2/3)

- A SceneBeans animation is described using XML
- Once an animation is started, it communicates with the surroundings using
  - **♦** commands
  - ♦ events
- SceneBeans is written in Java... why not try to use it?

### SceneBeans (3/3)

```
The interface of SceneBeans is:
sig
  val setAnimation: string -> int
  val getNextEvent: unit -> string
  val peekNextEvent: unit -> string
  val waitForEvent: string -> int
  val hasMoreEvents: unit -> bool
  val setValue:
       string * string * string -> int
  val invokeCommand: string -> int
end
                                    5<sup>th</sup> CPN Workshop – p. 38/56
```

#### **Definition of an XML File**

- We create an XML file describing the animation of our model
- Assuming we have a connection to a SceneBeans animation object named lights, we can load our XML file using:

```
lights.setAnimation("stop.xml");
```

## Clearing all High-lights

- In the XML file file, a clear command is defined
- The clear command can be invoked by: lights.invokeCommand("clear");

### High-lighting a Circle

- As the red, yellow, and green circles have an ID-attribute, we can change the value of their parameters
- We can change the value of the color-parameter of the red circle by:

```
lights.setValue(
    "red",
    "color",
    "ff0000");
```

### Waiting for User Input

- Whenever a user clicks on the green circle, an event is sent
- We can listen for events using: lights.getNextEvent();)

#### So Far, We Have Seen...

...how to use the SceneBeans animation object; in particular how to:

- create animation-description files
- load animation-description files
- invoke commands in the animation
- set parameters in the animation
- listen for events from the animation

#### More on SceneBeans

- The Telebit example from the start of the talk is created using the SceneBeans animation object
- Visit SceneBeans' homepage<sup>a</sup> for more information on writing animation-description files

ahttp://www-dse.doc.ic.ac.uk/Software/SceneBeans/

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#### A Closer Look at ShowModal

- It is easy to create an animation object:
  - 1. Create a Java class implementing a certain interface
  - 2. Generate appropriate ML code using rmicompiler

### Petri-net Based Prototyping (1/2)

- Using JBuilder, a very rough outline of a dialog is created
- A couple accessor methods are added
- Using the rmicompiler, an ML interface is created
- In 15 minutes, a nice dialog can be used from a net

## Petri-net Based Prototyping (2/2)

- This way it is easy to get input and present output
- We use Petri-nets to "program" the control flow
- Combining this, we obtain executable prototypes in a very easy manner

#### BRITNeY animation → MIMIC/CPN

MIMIC/CPN	BRITNeY animation
very general and low-level	encourages use of domain-specific, high-level animation objects <sup>a</sup>
animations can be designed using a GUI	(currently) no such feature
synchronous only	asynchronous features designed
extended by ML libraries	extended by ML libraries or by creating new animation objects in Java

<sup>&</sup>lt;sup>a</sup>But a number of quite general animation objects exist

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#### **Future Work**

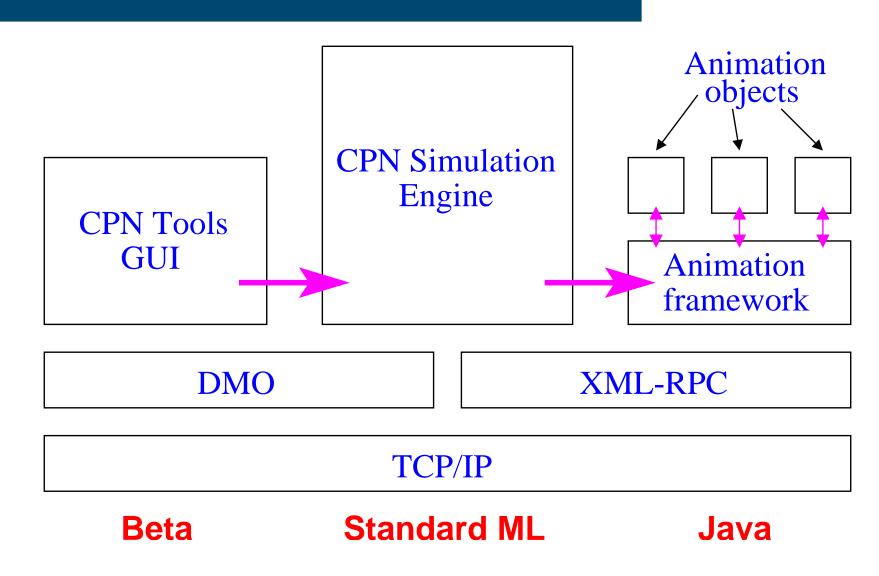
- Clean up and make 1<sup>st</sup> release
- Implementaiton of more animation objects
- New architecture

### **More Animation Objects**

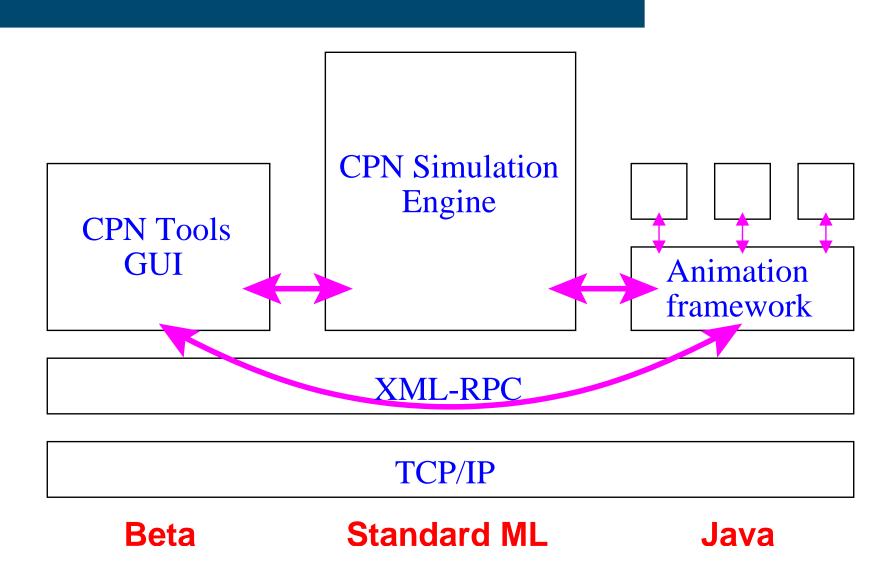
- Message sequence charts
- Charts (for use with e.g. the performance facilities)
- Report generator (to create nice simulation/state-space reports)
- Framemork for Petri-net based rapid prototyping
- PNVis (Kindler & Páles: 3D-Visualization of Petri Net Models)

• • • •

#### **Current Architecture**



#### **New Architecture**



#### **Benefits of the New Architecture**

- The simulation can be controlled better from the animation, by e.g. adding tokens to a place ⇒ the animation can run without the CPN Tools GUI
- Simulation can be started and stopped from the animation package
- Certain animations may be shown directly in the CPN Tools GUI
- Certain animations may be defined in CPN
   Tools and exported to the animation tool

### Summary

#### During this talk, we have seen

- How to create connections to animation objects
- A number of different animation objects
  - ♦ ShowModal
  - ♦ GetString
  - ♦ GraphSheet
  - ♦ SceneBeans
- How to use animations with nets
  - in code-fragments
  - ♦ to create extension-libraries